IP800-Series Insertion Paddlewheel Flow Sensor Instructions





General Information

General Information	Page 3
Features	Page 3
Specifications	Page 4
	5

Installation

Fitting Installation	Page 5
Meter Installation	Page 5
Straight Pipe Recommendations	Page 6
Full Pipe Recommendations	Page 7

Connections

Overview	Page 8
FT430	Page 8
FT440	Page 9
FT450	Page 9
FT4XX Sensus Tranceiver Connections	Page 9

Operation and Maintenance

Minimum Flow	Page 10
Flow Range Table	Page 10
Calibration ("K-Factor")	Page 10
Field Calibration	Page 10
Rotor Replacement	Page 11
Signal Troubleshooting	Page 11
Sensor Replacement	Page 11
Parts List	Page 12

Troubleshooting

Problems	Page 13
Probable Causes	Page 13
Things To Try	Page 13

Warranty

Seametrics Limited Warrant	٧	Page ²	14
	1		

The **IP800-Series** are impeller (or "paddlewheel") insertion meters designed for use with a wide variety of liquids in pipe sizes 1/2" to 8". Sensors are available in brass, 316 stainless steel, PVC, and polypropylene. Bodies are machined from a solid rod for maximum precision. Highquality jewel bearings and nickel-bound tungsten carbide shafts are used for extreme low friction and long life.

The rotation of the rotor is detected by a non-drag Halleffect sensor. Output is a current-sinking pulse, which can be sent long distances (up to 2,000 feet) without a transmitter. This signal can be connected directly to PLC's, counters, and computer cards, as well as a variety of Seametrics controls and displays.

Seametrics IP meters are ideal for chemical proportioning applications. For rate and total display, a modular system of electronics can be installed directly on the flow sensor

or mounted remotely. The FT430 (externally powered with pulse), FT440 (loop powered), and FT450 (battery powered) all provide digital rate and total displays, as well as a programmable pulse; the FT440 also provides a 4-20 mA analog output. Electronic modules can be wall- or metermounted.

The IP800-Series require special fittings that ensure correct depth placement in the pipe. Fittings come in a variety of materials for compatibility with specific applications. Tee fittings are individually wet-calibrated at the factory and marked with the K-factor (pulses per gallon). Saddle fittings must be field-installed on the pipe and do not come wet-calibrated. K-factors for saddles are based on factory-testing.

Features	
Electronics Module, Cover and Data Logger (Optional)	
Housing Screw	
Data Logger Port (optional)	
Cable Gland Strain Relief	
Powder-Coated Cast Aluminum Housingon Included when meter mounted electronics are ordered	
Retaining Slot (for U-Clip) (for easy installation at correct depth setting)	High Pressure Tee Fitting
O-Ring (EPDM, Viton [®] optional)	
Sensor Bodyo	
Jewel Bearings for superior low-flow performance	

Specfications*

Pipe Size		1/2" to 8"			
Power		Low Power: 6-36 Vdc/< 2 mA Micropowered (-04 Option): 3.1-16 Vdc/60 μA @ 3.6 Vdc			
Sensor		Low Power: Digital Magnetoresistiv	Low Power: Digital Magnetoresistive Micropowered (-04 Option): Giant Magnetoresistance (GMR)		
Materials	Optional Housing	Powder-coated cast aluminum			
	Sensor Body	Brass, 316 Stainless Steel, PVC, or Po	lypropylene		
	O-ring	EPDM (Viton® optional)			
	Rotor	PVDF (Kynar®)			
	Shaft	Kynar® /Tungsten Carbide (Kynar®	/Ceramic or Kynar®/Silicon Car	bide optional)	
	Bearings	Ruby jewel			
Maximum		Brass	316 Stainless Steel	PVC or Polypropylene (See Pressure vs. Temp. Chart)	
	Pressure	200 psi (13.8 bar)	200 psi (13.8 bar)	175 psi (12 bar) @ 75° F (24° C)	
	High Pressure	Not available	400 psi (27.6 bar)	Not available	
	Temperature	200° F (93° C)	200° F (93° C)	130° F (54.4° C)	
Flow Velocity		0.3 to 30 ft/sec (0.09 to 9.14 m/sec)			
Accuracy		± 1.5% of full scale			
Output Transi	istor Maximum Current Sinking	150mA (low power version only)			
Cable		#22 AWG 3-con, 18' (5.5m); 2,000' (609.6m) maximum cable run Note: 50' (15m) maximum for battery powered or micropowered versions.			
Environmenta	al	See meter mounted electronics specification for rating			
Regulatory		(€ Mark			

*Specifications subject to change • Please consult our website for current data (www.seametrics.com).

Kynar is a registered trademark of Arkema, Inc., Viton is a registered trademark of DuPont Corporation.



Caution: These flow sensors are not recommended for installation downstream of a boiler feedwater pump where installation fault may expose the flow sensor to boiler pressure and temperature. Maximum recommended temperature is 130°F (54.4°C), Plastic, 200°F (93°C), Metal.

Fitting Installation

The IP800-Series are fixed-depth meters that must be used with matched fittings appropriate to the application and pipe size. This ensures that the flow sensor is installed at the correct insertion depth to measure the average flow velocity of the stream.

Straight pipe of at least 10 diameters upstream and five diameters downstream of the meter is strongly recommended for proper accuracy. This is necessary because the shape of the velocity profile changes as the rate increases around an elbow; placing the meter too near the elbow causes a distorted reading. Additional straight run may be needed under specific adverse circumstances (see next page).

If you can't provide enough straight run to smooth out the velocity profile, some decrease in accuracy may result. This does not mean the meter's reading is meaningless, however. In some applications (e.g., control system, valve operation) a repeatable reading may be more important than a highly accurate one.



Stainless steel and brass fittings have female pipe threads, requiring the appropriate male threaded fittings. Saddle fittings require a hole to be cut in the pipe (recommended hole size is 1-3/4"). Before cutting into the pipe, observe the drawing below to choose your meter orientation.

A PVC fitting is usually installed by solvent welding. PVC tees are supplied with some upstream straight pipe, less than the recommended straight pipe requirements. It is not advisable to connect directly to the end of these fittings with a flow disturbing device (valve, elbow), but rather add straight pipe to the end of these fittings to meet the straight pipe requirements for your application.

Immersion

The IP800 Series standard sensors are not designed for continuous underwater operation. If this is a possibility, as in a flooded vault, a unit modified for immersion should be specified (Option -40), for temprary immersion.

Meter Installation

After the meter fitting is installed in the pipeline, the meter can be installed in the fitting. Press the meter into the fitting as far as it will go. Retain the meter in place by inserting the U-clip. The clip can be installed from either side. It may be necessary to rotate the probe back and forth slightly to start the clip into the slots on the probe. Slide the clip in as far as it will go.



Horizontal (3 o'clock or 9 o'clock position) is the preferred installation orientation, since it improves low-flow performance and avoids problems with trapped air and sediment. (See Orienting the Meter diagram below.) Bottom (6 o'clock) and top (12 o'clock) installations are acceptable if required by the piping layout.



Caution: Never remove the U-clip retainer when the pipe is under pressure. Always remove pressure from the pipe before you attempt to remove the meter. Removal under pressure may result in damage or serious injury.

Straight Pipe Recommendations (X = diameter)



Full Pipe Recommendations

Possible Problem



Allows air pockets to form at sensor

Possible Problem



Post-valve cavitation can create air pocket

Possible Problem



Air can be trapped

Possible Problem



Air can be trapped

Better Installation



Ensures full pipe

Better Installation



Keeps pipe full at sensor

Better Installation



Allows air to bleed off

Better Installation



Allows air to bleed off

Sensors are supplied with 18 ft. (5.5m) of cable. For sensors with no additional electronics, see diagram for color coding of connections. For sensors with on-board electronics, see the manual accompanying the electronic module.



FT430



FT440



FT450



FT4XX Sensus Tranceiver Connections

FT4XX Eqipped with Sensus Board (Side View)



Seametrics product at the factory. Longer cables are optional.

Calibration ("K-factor")

The K-factor represents the number of pulses per gallon the meter produces during a flow test. This number must be entered into your electronic control to make it read properly. If the IP800-Series meter is ordered with a **tee fitting**, it is factory-calibrated in the fitting and the K-factor is indicated on the side (see below).



Find Your K-Factor Here

If a **saddle** or **weld-type** fitting has been ordered, use the K-factor calculator at the bottom of the **seametrics.com** home page to determine the K-factor. In PVC, however, it is possible to order a saddle pre-installed on a standard length of pipe, and the fitting can be wet-calibrated in this case.

Field Calibration

It is possible to field-calibrate an IP800-Series flow sensor to determine an accurate K-factor in the actual installation. The reason for doing this would be to compensate for an unusual condition, for instance, applications with higher viscosity fluid (IP meters are calibrated for water use) or which lack adequate straight pipe ahead of the meter. Field Calibration procedures are described in a Technical Bulletin on our website (www.seametrics.com).



Minimum Flow

As with any other flow sensor, there is a rate below which the IP800-Series sensor cannot read. Check the flow rate table below for the minimum flow rate detectable by the sensor for a given pipe size.

Flow Range

Nominal Pipe Size	1⁄2″	3⁄4″	1″	1½″	2″	3″	4″	6″	8″
Min GPM	0.28	0.5	0.8	1.9	3.1	6.9	12	27	46.8
Min LPM	1.06	1.89	3.03	7.2	11.7	26.1	45	102	177
Max GPM	28	50	80	190	314	691	1190	2700	4680
Max LPM	106	189	302	719	1188	2615	4504	10221	17716



Caution: Never remove the u-clip retainer when the pipe is under pressure. Always remove pressure from the pipe before attempting to remove the meter. Removal under pressure may result in damage or serious injury.

Rotor Replacement

It is unusual for a rotor to require replacement due to damage sustained in normal service. More commonly, the meter is dropped while it is out of the pipe. Another reason for rotor replacement is shaft wear after long service. Rotors are easily field-replaced.

To install a rotor, follow these steps:

- 1. Unscrew the threaded bearing housings to expose the shaft ends. If bearings are being replaced, back them completely out.
- 2. Remove the rotor. Put the new rotor in its place.
- 3. Thread in one bearing housing part way, then the other. Take care to start the end of the shaft into the bearing hole before tightening further.
- 4. Screw in bearing housings until they bottom. Note: Do not use excessive force.
- 5. Check for free spin. Blowing lightly on the rotor should result in it spinning rapidly and coasting to a smooth stop.



Signal Troubleshooting

The flow sensor has only one moving part, the rotor. If this is turning properly and there is no signal, the magnetic sensor is not operating properly. To check the signal, apply 12 Vdc power to the red (+) and black (-) leads. Set a multimeter to voltage reading. Put the positive multimeter lead on the red wire and the negative lead on the white wire. Slowly turn the rotor. Voltage reading should swing between +12 Volts and 0 Volts as the rotor turns. If it does not, the solid-state magnetic sensor is not working properly. Checking for continuity is not a useful test of these sensors.

Sensor Replacement

It is very unusual for a sensor to require replacement in normal use. The primary cause of sensor failure is overvoltage (inadvertent connection of high voltage, for example) or incorrect polarity on hookup. The sensor is replaced by removing the strain relief, then threading out the sensor retainer plug. Remove the entire sensor capsule by pulling on the cable. The new sensor capsule can then be installed. Replace the retainer plug, and then replace and tighten the strain relief.



IP800-Series Parts List



IP80	0 Series Parts	
1	Upper housing/ electronics	Contact service representative for your specific model
2	Housing gasket/seal	102025
3	Lower housing	Not field replaceable
4	Housing screw/washer kit (4 each)	100414
5	Plug, steel (battery units)	100360
6	Strain relief kit, small (includes 2)	100364
7	Strain relief kit, large (includes 1) (externally powered units)	101850
8	Sensor pickup	100508 (Micropower, gray cable, FT450) 100419 (Standard, blue cable, FT430/440)
9	Sensor retaining screw	100298
10a	U-clip, retainer	100154
10b	High pressure retaining clip (requires 2)	101776
11	O-ring	100264 (EPDM)
12	Body	See distributor
13	Bearings (includes 2)	103315
14	Rotor with shaft	Order Rotor Repair Kit
15	Rotor repair kit (#13 & #14 above)	100317 (Kynar®/tungsten carbide) 100043 (Kynar®/ceramic) 100556 (Kynar®/silicone carbide)

Problem	Probable Cause	Things to Try
No signal after installation	Insufficient flow	Consult Flow Rate Chart Reduce pipe size or use different sensor
	Bad connections to control electronics	Check connections at control: Red (+), Black (-), White (signal)
	Incompatible control	Use 6-36 Vdc power supply - for low power Use 3.1-16 Vdc power supply - for micropowered Add pull up resistor, if using current-sourcing device
	Damaged or missing rotor	Remove flow sensor from fitting and check for free spinning; replace rotor
	Failed magnetic sensor	See Signal Troubleshooting (page 11); replace magnetic sensor
Inaccurate metering	Not enough straight pipe between meter and severe flow disturbance	Move meter away from flow disturbance or field calibrate
	Wrong K-Factory entered	Check fitting for K-Factor, check indicator to see if it is entered properly ("Set K" on FT430, FT440, FT450, or FT520)
	Magnetic sensor failing to pick up each blade	Remove flow sensor from pipe. If indicator is FT430, FT440, FT450, or FT520, set K to 1.00, turn rotor slowly by hand, indicator should cound each blade; replace sensor
	Wrong time units on flow indicator	If using FT430, FT440, or FT520, check left side of display (sec, min, hr, day); change to desired unit

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- b. Any defective part or parts must be returned to Seametrics' factory or to an authorized service center for inspection.
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- e. Seametrics will deliver repaired products or replacements for defective products to the buyer (ground freight prepaid) to the destination provided in the original order.
- f. Products returned to Seametrics for which Seametrics provides replacement under this warranty shall become the property of Seametrics.
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 - ii. Failure to follow operating, maintenance, or environmental instructions prescribed in Seametrics' instruction manual
 - iii. Products not used for their intended purpose
 - iv. Alterations to the product, purposeful or accidental
 - v. Electrical current fluctuations
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- h. A new warranty period will be established for repaired products, or products replaced during the original warranty period.
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