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The **PT12-BV** comes as a weatherproof stand-alone box or with an automatic compensation wiring option. The PT12-BV measures pressure, temperature, and supply voltage.

The weatherproof box is an ideal barometric reference for absolute pressure sensors. This version features both an SDI-12 interface and a Modbus® RTU interface that makes the product easy to connect to recorders and operates on low power. This makes it a preferred choice for many environmental professionals with existing SDI-12 or Modbus® RTU systems.

With the Compensation Wiring Option, the PT12-BV automatically provides barometric compensation for a single attached absolute PT12 submersible pressure sensor. **No post processing of data. No need to use a vented cable or worry about maintaining desiccant tubes.** This version features an SDI-12 communication interface, making it ideal for many existing environmental systems.

---

**Dimensions**

![Diagram of PT12-BV dimensions]
# Specifications*

<table>
<thead>
<tr>
<th>Specification</th>
<th>Details</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Housing</strong></td>
<td><strong>Material</strong> Weatherproof box - ABS - IP66/67</td>
</tr>
<tr>
<td></td>
<td><strong>Dimensions</strong> Box only: 4.3” x 3.1” x 2.6” (11 x 8 x 6.5 cm)</td>
</tr>
<tr>
<td></td>
<td><strong>Wire Seal Material</strong> Fluorocarbon and Buna N</td>
</tr>
<tr>
<td></td>
<td><strong>Communication Pigtail</strong> 5 ft (1.5 m) polyurethane cable</td>
</tr>
<tr>
<td><strong>Options</strong></td>
<td>PT12-BV compensation wiring option; Bulkhead connector</td>
</tr>
<tr>
<td><strong>Temperature</strong></td>
<td><strong>Operating Range</strong> Recommended: -15˚ to 55˚C (5˚ to 131˚F) Not designed to operate under water</td>
</tr>
<tr>
<td></td>
<td><strong>Storage Range</strong> -40˚ to 80˚C (-40˚ to 176˚F)</td>
</tr>
<tr>
<td><strong>Power</strong></td>
<td><strong>Voltage</strong> 9-15Vdc, 24Vdc over voltage protection, electromagnetic &amp; transient protection IEC-61000 - 4-3, 4-4, 4-5, 4-6</td>
</tr>
<tr>
<td></td>
<td><strong>Supply Current</strong> Active 3mA average/ 10mA peak; sleep 150 µA</td>
</tr>
<tr>
<td><strong>Communication</strong></td>
<td><strong>Modbus®</strong> RS485 Modbus® RTU, output=32bit IEEE floating point</td>
</tr>
<tr>
<td></td>
<td><strong>SDI-12</strong> SDI-12 (ver. 1.3) - ASCII</td>
</tr>
<tr>
<td><strong>Output Channels</strong></td>
<td><strong>Temperature</strong> Digital IC on board</td>
</tr>
<tr>
<td></td>
<td><strong>Pressure/Vacuum</strong> Silicon strain gauge transducer, 316 stainless</td>
</tr>
<tr>
<td></td>
<td><strong>Accuracy</strong> ±0.5°C — 0˚ to 55°C (32˚ to 131˚F) ±0.05% FSO (typical, static) ±0.1% FSO (maximum, static) (B.F.S.L. 20˚C)</td>
</tr>
<tr>
<td></td>
<td><strong>Resolution</strong> 0.06˚C 0.0034% FS (typical)</td>
</tr>
<tr>
<td></td>
<td><strong>Range</strong> -15˚ to 55˚C (5˚ to 131˚F) 0-16 psia (110 kpa)</td>
</tr>
<tr>
<td></td>
<td><strong>Compensated</strong> --- 0˚ to 40˚C (32˚ to 104˚F)</td>
</tr>
<tr>
<td><strong>Over pressure protection</strong></td>
<td>2x</td>
</tr>
<tr>
<td><strong>Environmental</strong></td>
<td><strong>IP66/67</strong></td>
</tr>
</tbody>
</table>

*Specifications subject to change. Please consult our website for the most current data (Seametrics.com). Modbus is a registered trademark of Schneider Electric.
How Pressure Sensors Work

Liquids and gasses do not retain a fixed shape. Both have the ability to flow and are often referred to as fluids. One fundamental law for a fluid is that the fluid exerts an equal pressure in all directions at a given level. Further, this pressure increases with an increasing depth of "submergence". If the density of a fluid remains constant (noncompressible...a generally good assumption for water at "normal" pressures and temperatures), this pressure increases linearly with the depth of "submergence".

We are all "submerged" in the atmosphere. As we increase our elevation, the pressure exerted on our bodies decreases as there is less of this fluid above us. It should be noted that atmospheric pressure at a given level does vary with changes in the weather. One standard atmosphere (pressure at sea level at 20º C) is defined to be 14.7 PSI (pounds per square inch).

There are several methods to reference a pressure measurement. Absolute pressure is measured with respect to an ideal vacuum (no pressure). Gauge pressure is the most common way we express pressure in every day life and is the pressure exerted over and above atmospheric pressure. With this in mind, gauge pressure (Pg) can be expressed as the difference between the absolute pressure (Pa) and atmospheric pressure (Patm):

\[ Pg = Pa - Patm. \]

To measure gauge pressure, atmospheric pressure is subjected to one side of the system and the pressure to be measured is subjected to the other. The result is that the differential (gauge pressure) is measured. A tire pressure gauge is a common example of this type of device.

Recall that as the level of submergence increases (in a noncompressible fluid), the pressure increases linearly. Also, recall that changes in weather cause the absolute atmospheric pressure to change. In water, the absolute pressure (Pa) at some level of depth (d) is given as follows:

\[ Pa = Patm + kd \]

where k is simply a constant (i.e.: 2.307 feet of water = 1 PSI)

Seametrics standard gauge submersible pressure devices utilize a vent tube in the cable to allow the device to reference atmospheric pressure. The resulting gauge pressure measurement reflects only the depth of submergence. That is, the net pressure on the diaphragm is due entirely to the depth of submergence.

Pressure Diagram: See Detail A.

Absolute pressure is given as \( Pa = Patm + kd \) (where \( k \) is 2.307 feet of water)
General Information/Installation

Initial Inspection and Handling
Upon receipt of your sensor, inspect the shipping package for damage. If any damage is apparent, note the signs of damage on the appropriate shipping form. After opening the carton, look for concealed damage, such as a cut cable. If concealed damage is found, immediately file a claim with the carrier.

Do’s and Don’ts

- Do handle sensor with care
- Do protect from excessive sun or heat
- Don’t install so box or connector is submerged
- Don’t bang or drop on hard objects

Installing the Sensor

For Barometric Measurement
The PT2X-BV box version can be installed in any position; however, it is tested at the factory in the vertical position. Therefore, when installing the transmitter outdoors, Seametrics recommends installing it in a vertical position to avoid moisture entering the inlet. Seametrics also recommends installing a sun shield to avoid overheating.

For Vacuum Measurement
If installing a vacuum tube for vacuum measurements, be sure that the tubing is not collapsible. The box unit is provided with a detachable Quick-Connect (QC) with a male 1/8” pipe fitting. Attach the tubing to the QC using an appropriate tube fitting for the tubing chosen. Attach a fitting to the inlet male QC designed to seal the tubing of your choice. Seal the fitting to the QC by using sealant or PTFE tape. Connect the male QC to the inlet QC of the PT2X-BV and the other end of the tube to the vacuum source using appropriate fittings.
**Wiring for Barometric Compensation Units (SDI-12 only)**

When wired for automatic barometric compensation, the surface installed PT12-BV communicates with the down-hole PT12 Pressure/Temperature Sensor via Modbus®. The surface PT12-BV then communicates via SDI-12 with an external SDI-12 host or logger to give compensated pressure readings for the down-hole sensor. (See the Operation/SDI-12 section for SDI-12 command information.)

**Grounding Issues**

It is commonly known that when using electronic equipment, both personnel and equipment need to be protected from high power spikes that may be caused by lightning, power line surges, or faulty equipment. Without a proper grounding system, a power spike will find the path of least resistance to earth ground—whether that path is through sensitive electronic equipment or the person operating the equipment. In order to ensure safety and prevent equipment damage, a grounding system must be used to provide a low resistance path to ground.

When using several pieces of interconnected equipment, each of which may have its own ground, problems with noise, signal interference, and erroneous readings may be noted. This is caused by a condition known as a **Ground Loop**. Because of natural resistance in the earth between the grounding points, current can flow between the points, creating an unexpected voltage difference and resulting erroneous readings.

The **single most important step** in minimizing a ground loop is to tie all equipment (sensors, data loggers, external power sources, and any other associated equipment) to a single common grounding point.

**Sensor/Data Logger Configuration**

The PT12-BV is designed for use with SDI-12 or Modbus® data loggers.

Every sensor is individually calibrated at the factory, using an environmental test chamber and dead-weight tester. Sensor specific calibration values are stored in the sensor. When taking measurements, the internal microprocessor uses these calibration values to thermally compensate the pressure readings.

In addition to the factory set calibration values, the user can enter a field calibration slope and offset for the pressure and temperature channels. Pressure readings default to psi and temperature readings to degrees Celsius. The user can enter a units conversion slope and offset to change units, if desired. See the operation sections for details on changing these values. The power supply voltage channel always returns values in volts.
This section explains how to read your PT12-BV via Modbus® RTU. (If you want to read via SDI-12, see the next section beginning on page 10.)

NOTE: Modbus® is not available if using the Compensation Wiring Option.

### Power Consideration
If your sensor is not powered continuously by an auxiliary power supply, then you must turn power on to the sensor at least two seconds before a reading is to be taken to allow the sensor to warm up.

### Communication Settings
The PT12-BV is configured to communicate with 8 data bits, one stop bit, and no parity. Default baud rate is 19200.

### Modbus® Functions
All readings are obtained using Modbus® function 03-Read Holding Registers. Readings are located in two registers each. The data is returned as a 32-bit IEEE floating-point value, high word first, also referred to as big-endian, float inverse, or Float AB CD.

#### Channel Registers Using Standard Addressing

<table>
<thead>
<tr>
<th></th>
<th>Zero-Based</th>
<th>One-Based</th>
<th>+40,001</th>
<th>+400,001</th>
</tr>
</thead>
<tbody>
<tr>
<td>Pressure</td>
<td>0</td>
<td>1</td>
<td>40001</td>
<td>400001</td>
</tr>
<tr>
<td>Temperature</td>
<td>2</td>
<td>3</td>
<td>40003</td>
<td>400003</td>
</tr>
<tr>
<td>Power Supply Voltage</td>
<td>4</td>
<td>5</td>
<td>40005</td>
<td>400005</td>
</tr>
<tr>
<td>Averaged Pressure</td>
<td>6</td>
<td>7</td>
<td>40007</td>
<td>400007</td>
</tr>
<tr>
<td>Maximum Pressure</td>
<td>8</td>
<td>9</td>
<td>40009</td>
<td>400009</td>
</tr>
<tr>
<td>Minimum Pressure</td>
<td>10</td>
<td>11</td>
<td>40011</td>
<td>400011</td>
</tr>
<tr>
<td>Averaged Temperature</td>
<td>12</td>
<td>13</td>
<td>40013</td>
<td>400013</td>
</tr>
</tbody>
</table>

#### Channel Registers Using High Addressing—

(For compatibility with other Seametrics Smart Sensor equipment, the PT12-BV also returns these same readings starting at a register address 62592 (or 62593 if using one-based addressing).)

<table>
<thead>
<tr>
<th></th>
<th>Zero-Based</th>
<th>One-Based</th>
<th>+40,001</th>
</tr>
</thead>
<tbody>
<tr>
<td>Pressure</td>
<td>62592</td>
<td>62593</td>
<td>462593</td>
</tr>
<tr>
<td>Temperature</td>
<td>62594</td>
<td>62595</td>
<td>462595</td>
</tr>
<tr>
<td>Power Supply Voltage</td>
<td>62596</td>
<td>62597</td>
<td>462597</td>
</tr>
<tr>
<td>Averaged Pressure</td>
<td>62598</td>
<td>62599</td>
<td>462599</td>
</tr>
<tr>
<td>Maximum Pressure</td>
<td>62600</td>
<td>62601</td>
<td>462601</td>
</tr>
<tr>
<td>Minimum Pressure</td>
<td>62602</td>
<td>62603</td>
<td>462603</td>
</tr>
<tr>
<td>Averaged Temperature</td>
<td>62604</td>
<td>62605</td>
<td>462605</td>
</tr>
</tbody>
</table>

### Register Definitions
The physical register addresses on the PT12-BV start numbering from zero – the first address is 0, the second is 1, etc. On the other hand, Modbus® protocol considers the first logical address to be 1, the second logical address to be 2, etc. For example, to take a pressure reading you have to read the physical address 0.

Some programs and equipment when asked to read address 0 will read that physical address. Others however will read that logical address, which is actually the physical address -1 (which does not exist). With these programs and equipment you must add a one to the address – thus in this example you would request a read at address 1.

Still other programs and equipment require the addition of 40,000 or 400,000 to the address to indicate reading holding registers. These usually also require the addition of one to the physical address. Check with your program and/or equipment documentation to determine what style of register addressing is required.
Sensor Configuration/Control

<table>
<thead>
<tr>
<th>Description</th>
<th>Zero-Based</th>
<th>One-Based</th>
<th>+40,001</th>
</tr>
</thead>
<tbody>
<tr>
<td>Set <strong>averaging</strong>. This enables sensor for <strong>n</strong> seconds. Each second, the statistical data registers will be updated to contain new averages, max and min. At the completion of <strong>n</strong> seconds, the final statistical values will be left in the registers, and the sensor will be put to sleep. <strong>n</strong> = 0.10,800. If <strong>n</strong> = 0, the sensor is put to sleep, and the statistical data values are not updated.</td>
<td>300=n</td>
<td>301=n</td>
<td>40301=n</td>
</tr>
<tr>
<td>Set <strong>sensor address</strong> = a (Write Only)</td>
<td>400=a</td>
<td>401=a</td>
<td>40401=a</td>
</tr>
<tr>
<td>Set <strong>baud rate</strong> = b (Write only) 0=38400, 1=19200 (default), 2=9600, 3=4800, 4=2400, 5=1200</td>
<td>500=b</td>
<td>501=b</td>
<td>40501=b</td>
</tr>
<tr>
<td>Set <strong>auto-enable</strong>. Causes sensor to be enabled automatically for <strong>w</strong> seconds after a read of any parameter data register. <strong>W</strong>=0 disables auto-enable. (This is normally set to 10 seconds at the factory.) For lowest power usage, set this to zero. For fastest readings while still retaining as much power savings as possible, set slightly longer than your read frequency. See section below for information on how this setting affects your readings.</td>
<td>600=w</td>
<td>601=w</td>
<td>40601=w</td>
</tr>
<tr>
<td>Set <strong>serial number</strong>. <strong>L</strong>= unsigned longword value 0x00000000 .. 0xFFFFFFFF (0 .. 4,294,967,295)</td>
<td>700=L</td>
<td>701=L</td>
<td>40701=L</td>
</tr>
<tr>
<td>Read <strong>sensor firmware revision</strong>. Word MSB = Major revision, LSB = minor revision. E.g., 0013 = revision 0.13</td>
<td>800</td>
<td>801</td>
<td>40801</td>
</tr>
</tbody>
</table>

Readings and the Auto-Enable Setting

When a reading is requested, four things happen:

- The sensor wakes up.
- The current value in the register is returned.
- The sensor turns on the analog portion, begins sampling, and begins putting the new values in the registers.
- If auto-enable is set to a positive value **w**, the sensor stays awake for **w** seconds, sampling and moving values into the registers all the while, and then goes to sleep.
- If auto-enable is set to zero, the sensor immediately goes to sleep after putting the reading in the register.

If your read frequency is less than the auto-enable value, the sensor will stay on continuously, and your readings will always be fresh, with the exception of the very first reading.

If your read frequency is greater than the auto-enable value, the following reading sequence is recommended:

1. Request a reading. This begins the wakeup process on the sensor and returns the value currently in the register, which will be old data. Throw this value away.

2. Wait one second, then take another reading. This reading will have fresh data. Record this reading.

Calibration and Conversion Constants

The data is returned as a 32-bit IEEE floating-point value, high word first, also referred to as big-endian, float inverse, or Float AB CD.

Field calibration values and units conversion values can be set by the user. If set, these values will be applied to the readings before values are returned.

<table>
<thead>
<tr>
<th>Description</th>
<th>Zero-Based</th>
<th>One-Based</th>
<th>+40,001</th>
</tr>
</thead>
<tbody>
<tr>
<td>Factory Calibration* - Pressure Scale</td>
<td>200-01</td>
<td>201-02</td>
<td>40201-02</td>
</tr>
<tr>
<td>Factory Calibration* - Pressure Linearization 1</td>
<td>202-03</td>
<td>203-04</td>
<td>40203-04</td>
</tr>
<tr>
<td>Factory Calibration* - Pressure Linearization 2</td>
<td>204-05</td>
<td>205-06</td>
<td>40205-06</td>
</tr>
<tr>
<td>Factory Calibration* - Pressure Slope 0</td>
<td>206-07</td>
<td>207-08</td>
<td>40207-08</td>
</tr>
<tr>
<td>Factory Calibration* - Pressure Slope 1</td>
<td>208-09</td>
<td>209-10</td>
<td>40209-10</td>
</tr>
<tr>
<td>Factory Calibration* - Pressure Slope 2</td>
<td>210-11</td>
<td>211-12</td>
<td>40211-12</td>
</tr>
<tr>
<td>Factory Calibration* - Pressure Offset 0</td>
<td>212-13</td>
<td>213-14</td>
<td>40213-14</td>
</tr>
<tr>
<td>Factory Calibration* - Pressure Offset 1</td>
<td>214-15</td>
<td>215-16</td>
<td>40215-16</td>
</tr>
<tr>
<td>Factory Calibration* - Pressure Offset 2</td>
<td>216-17</td>
<td>217-18</td>
<td>40217-18</td>
</tr>
<tr>
<td>Field Calibration - Pressure Slope</td>
<td>218-19</td>
<td>219-20</td>
<td>40219-20</td>
</tr>
<tr>
<td>Field Calibration - Pressure Offset</td>
<td>220-21</td>
<td>221-22</td>
<td>40221-22</td>
</tr>
<tr>
<td>Field Calibration - Temperature Slope</td>
<td>222-23</td>
<td>223-24</td>
<td>40223-24</td>
</tr>
<tr>
<td>Field Calibration - Temperature Offset</td>
<td>224-25</td>
<td>226-26</td>
<td>40225-26</td>
</tr>
<tr>
<td>Field Calibration - Temperature Alpha</td>
<td>226-27</td>
<td>227-28</td>
<td>40227-28</td>
</tr>
<tr>
<td>Temperature Alpha</td>
<td>228-29</td>
<td>229-30</td>
<td>40229-30</td>
</tr>
<tr>
<td>Factory Calibration* - Temperature Offset</td>
<td>230-31</td>
<td>231-32</td>
<td>40231-32</td>
</tr>
<tr>
<td>Factory Calibration* - Temperature Slope</td>
<td>232-33</td>
<td>233-34</td>
<td>40233-34</td>
</tr>
<tr>
<td>Pressure Units - Conversion Slope</td>
<td>234-35</td>
<td>235-36</td>
<td>40235-36</td>
</tr>
<tr>
<td>Temperature Units - Conversion Offset</td>
<td>236-37</td>
<td>237-38</td>
<td>40237-38</td>
</tr>
<tr>
<td>Temperature Units - Conversion Slope</td>
<td>238-39</td>
<td>239-40</td>
<td>40239-40</td>
</tr>
</tbody>
</table>

* Factory calibration values are set at the factory.

Writing to Factory Calibration registers will void calibration!
OPERATION/SDI-12

Reading via SDI-12

Addressing
Default SDI-12 Address: 0

SDI-12 Command Nomenclature
- `<a>` = Sensor address
- `{crc}` = SDI-12 compatible 3-character CRC
- `<cr>` = ASCII carriage return character
- `<lf>` = ASCII line feed character

**highlighted values** indicate variable data

SDI-12 Commands

Sensor Identification

```
<a>! <a>13 INWUSA PT12 0.13ssssssss<cr><lf>
```

Note: 0.13 will change to reflect current firmware version.

ssssssss = device serial number

Acknowledge Active, Address Query

```
<a>! <a><cr><lf>
?! <a><cr><lf>
```

Change Address

```
<a>A<b>! <b><cr><lf>
```

Change address to `<b>`

Request Measurement

```
<a>M! <a>0023<cr><lf>
<a>D0! <a>+7.15863+25.0000+12.0512<cr><lf>
```

Request all basic measurements

Read: pressure, temperature, voltage

```
<a>M1! <a>0021<cr><lf>
<a>D0! <a>+7.15863<cr><lf>
```

Request pressure measurement only

Read pressure

```
<a>M2! <a>0021<cr><lf>
<a>D0! <a>+25.0000<cr><lf>
```

Request temperature measurement only

Read temperature

```
<a>M3! <a>0021<cr><lf>
<a>D0! <a>+12.0512<cr><lf>
```

Request power supply voltage

Read power supply voltage

```
<a>M4! <a>0ttt4<cr><lf>
<a>D0! <a>+7.15863+7.23215+7.051283+25.0000<cr><lf>
```

Request averaged data. ttt depends on programmed average duration.

Read average pressure, max. pressure, min. pressure, average temperature
M5!, M6!, and M7! only available on PT12-BV/PT12 combination units!

<a>M5! <a>0023<cr><lf>
Request barometrically compensated down-hole pressure, down-hole temperature, surface temperature

<a>D0! <a>+2.58613+19.2100+21.05122<cr><lf>
Read: barometrically compensated down-hole pressure, down-hole temperature, surface temperature

<a>M6! <a>0024<cr><lf>
Request non-barometrically compensated down-hole pressure, down-hole temperature, surface pressure, surface temperature

<a>D0! <a>+17.31813+19.2100+14.732+21.0512<cr><lf>
Read non-barometrically compensated down-hole pressure, down-hole temperature, surface pressure, surface temperature

<a>M7! <a>ttt1<cr><lf>
Request averaged barometrically compensated pressure. ttt depends on programmed average.

<a>D0! <a>+7.12050<cr><lf>
Read temperature averaged barometrically compensated pressure

Request Measurement with CRC

<a>MC! <a>0023<cr><lf>
Request all basic measurements

<a>D0! <a>+7.15863+25.0000+12.0512{crc}<cr><lf>
Read: pressure, temperature, voltage

<a>MC1! <a>0021<cr><lf>
Request pressure measurement only

<a>D0! <a>+7.15863{crc}<cr><lf>
Read pressure

<a>MC2! <a>0021<cr><lf>
Request temperature measurement only

<a>D0! <a>+25.0000{crc}<cr><lf>
Read temperature

<a>MC3! <a>0021<cr><lf>
Request power supply voltage

<a>D0! <a>+12.0512{crc}<cr><lf>
Read power supply voltage

<a>MC4! <a>0ttt4<cr><lf>
Request averaged data. ttt depends on programmed average duration.

<a>D0! <a>+7.15863+7.23215+7.051283+25.0000{crc}<cr><lf>
Read average pressure, max. pressure, min. pressure, average temperature

MC5!, MC6!, and MC7! only available on PT12-BV/PT12 combination units!

<a>MC5! <a>0023<cr><lf>
Request barometrically compensated down-hole pressure, down-hole temperature, surface temperature

<a>D0! <a>+2.58613+19.2100+21.05122{crc}<cr><lf>
Read: barometrically compensated down-hole pressure, down-hole temperature, surface temperature

<a>MC6! <a>0024<cr><lf>
Request non-barometrically compensated down-hole pressure, down-hole temperature, surface pressure, surface temperature

<a>D0! <a>+17.31813+19.2100+14.732+21.0512{crc}<cr><lf>
Read non-barometrically compensated down-hole pressure, down-hole temperature, surface pressure, surface temperature

<a>MC7! <a>ttt<cr><lf>
Request averaged data. ttt depends on programmed average duration.

<a>D0! <a>+7.15863<cr><lf>
Read temperature averaged barometrically compensated pressure

Request Measurement with CRC
<a>MC7! <a>ttt1<cr><lf>

Request averaged barometrically compensated pressure. ttt depends on programmed average.

Read temperature averaged barometrically compensated pressure

Concurrent Measurement

<a>C! <a>0023<cr><lf>

Request all basic measurements

Read: pressure, temperature, voltage

<a>D0! <a>+7.15863+25.0000+12.0512<cr><lf>

<a>C1! <a>0021<cr><lf>

Request pressure measurement only

Read pressure

<a>D0! <a>+7.15863<cr><lf>

<a>C2! <a>0021<cr><lf>

Request temperature measurement only

Read temperature

<a>D0! <a>+25.0000<cr><lf>

<a>C3! <a>0021<cr><lf>

Request power supply voltage

Read power supply voltage

<a>D0! <a>+12.0512<cr><lf>

<a>C4! <a>0ttt4<cr><lf>

Request averaged data. ttt depends on programmed average duration.

Read average pressure, max. pressure, min. pressure, average temperature

C5!, C6!, and C7! only available on PT12-BV/PT12 combination units!

<a>C5! <a>0023<cr><lf>

Request barometrically compensated down-hole pressure, down-hole temperature, surface temperature

Read: barometrically compensated down-hole pressure, down-hole temperature, surface temperature

<a>D0! <a>+2.58613+19.2100+21.05122<cr><lf>

Request non-barometrically compensated down-hole pressure, down-hole temperature, surface pressure, surface temperature

Read non-barometrically compensated down-hole pressure, down-hole temperature, surface pressure, surface temperature

<a>C6! <a>0024<cr><lf>

Request averaged barometrically compensated pressure. ttt depends on programmed average.

Read temperature averaged barometrically compensated pressure

<a>D0! <a>+7.12050<cr><lf>

<a>C7! <a>ttt1<cr><lf>

<a>D0! <a>+7.12050<cr><lf>
**Concurrent Measurement with CRC**

```plaintext
<a>CC! <a>0023<cr><lf>
<a>D0! <a> +7.15863+25.0000+12.0512{crc}<cr><lf>
```
Request all basic measurements
Read: pressure, temperature, voltage

```plaintext
<a>CC1! <a>0021<cr><lf>
<a>D0! <a> +7.15863<cr><lf>
```
Request pressure measurement only
Read pressure

```plaintext
<a>CC2! <a>0021<cr><lf>
<a>D0! <a> +25.0000<cr><lf>
```
Request temperature measurement only
Read temperature

```plaintext
<a>CC3! <a>0021<cr><lf>
<a>D0! <a> +12.0512<cr><lf>
```
Request power supply voltage
Read power supply voltage

```plaintext
<a>CC4! <a>0ttt4<cr><lf>
<a>D0! <a> +7.15863+7.23215+7.051283+25.0000<cr><lf>
```
Request averaged data. ttt depends on programmed average duration.
Read average pressure, max. pressure, min. pressure, average temperature

**CC5!, CC6!, and CC7! only available on PT12-BV/PT12 combination units!**

```plaintext
<a>CC5! <a>0023<cr><lf>
<a>D0! <a> +7.15863+19.2100+21.05122<cr><lf>
```
Request barometrically compensated down-hole pressure, down-hole temperature, surface temperature
Read: barometrically compensated down-hole pressure, down-hole temperature, surface temperature

```plaintext
<a>CC6! <a>0024<cr><lf>
<a>D0! <a> +17.31813+19.2100+14.732+21.0512<cr><lf>
```
Request non-barometrically compensated down-hole pressure, down-hole temperature, surface pressure, surface temperature
Read non-barometrically compensated down-hole pressure, down-hole temperature, surface pressure, surface temperature

```plaintext
<a>CC7! <a>ttt1<cr><lf>
<a>D0! <a> +7.12050<cr><lf>
```
Request averaged barometrically compensated pressure. ttt depends on programmed average.
Read temperature averaged barometrically compensated pressure

**Extended Commands**

*Set duration for averaging reading*

```plaintext
<a>XA<ttt!<a>ttt<cr><lf>
```
Set duration of averaged data for M4, MC4, C4, and CC4 commands. ttt = 1–997 seconds

*Read/Modify Calibration Values*

```plaintext
<a>XCnn=[<value>]<cr><lf>
```
Read (modify) calibration value nn

Examples:

```plaintext
<a>XC00! <a> +1.591600e-5<cr><lf>
<a>XC00=1.704e-4! <a> +1.704000e-4<cr><lf>
```
Read the value from calibration register 00
Set the value of calibration register 00

*Set number of significant digits*

```plaintext
<a>XS<ttt!<a><ttt<cr><lf>
```
Set number of significant digits for SDI-12 report data. tt = 1–7
**Calibration Register Definitions**

Field calibration values can be set by user. If set, these values will be applied to readings before values are returned. All calibration registers contain floating point values.

<table>
<thead>
<tr>
<th>SDI-12 Reg. ID</th>
<th>Mnemonic</th>
<th>Description</th>
<th>Default value</th>
</tr>
</thead>
<tbody>
<tr>
<td>00</td>
<td>Scale</td>
<td>Units scale ((counts \times \text{Scale} = \text{base units, default psi}))</td>
<td>1.591600e-5</td>
</tr>
<tr>
<td>01</td>
<td>a</td>
<td>Factory calibration linearized correction factor (1^*)</td>
<td>0.000000e+00</td>
</tr>
<tr>
<td>02</td>
<td>b</td>
<td>Factory calibration linearized correction factor (2^*)</td>
<td>1.000000e+00</td>
</tr>
<tr>
<td>03</td>
<td>m0</td>
<td>Factory calibration slope coefficient (0^*)</td>
<td>1.000000e+00</td>
</tr>
<tr>
<td>04</td>
<td>m1</td>
<td>Factory calibration slope coefficient (1^*)</td>
<td>0.000000e+00</td>
</tr>
<tr>
<td>05</td>
<td>m2</td>
<td>Factory calibration slope coefficient (2^*)</td>
<td>0.000000e+00</td>
</tr>
<tr>
<td>06</td>
<td>b0</td>
<td>Factory calibration offset coefficient (0^*)</td>
<td>0.000000e+00</td>
</tr>
<tr>
<td>07</td>
<td>b1</td>
<td>Factory calibration offset coefficient (1^*)</td>
<td>0.000000e+00</td>
</tr>
<tr>
<td>08</td>
<td>b2</td>
<td>Factory calibration offset coefficient (2^*)</td>
<td>0.000000e+00</td>
</tr>
<tr>
<td>09</td>
<td>mField</td>
<td>Field pressure calibration slope</td>
<td>1.000000e+00</td>
</tr>
<tr>
<td>10</td>
<td>bField</td>
<td>Field pressure calibration offset</td>
<td>0.000000e+00</td>
</tr>
<tr>
<td>11</td>
<td>mT</td>
<td>Field temperature calibration slope</td>
<td>1.000000e+00</td>
</tr>
<tr>
<td>12</td>
<td>bT</td>
<td>Field temperature calibration offset</td>
<td>0.000000e+00</td>
</tr>
<tr>
<td>13</td>
<td>T_Alpha</td>
<td>Factory temperature calibration–Alpha(^*)</td>
<td>0.000000e+00</td>
</tr>
<tr>
<td>14</td>
<td>T_Offset</td>
<td>Factory temperature calibration–Offset(^*)</td>
<td>0.000000e+00</td>
</tr>
<tr>
<td>15</td>
<td>T-ZeroSlope</td>
<td>Factory temperature calibration–ZeroSlope(^*)</td>
<td>0.000000e+00</td>
</tr>
<tr>
<td>16</td>
<td>P_mUnits</td>
<td>Pressure units conversion slope</td>
<td>1.000000e+00</td>
</tr>
<tr>
<td>17</td>
<td>P_bUnits</td>
<td>Pressure units conversion offset</td>
<td>0.000000e+00</td>
</tr>
<tr>
<td>18</td>
<td>T_mUnits</td>
<td>Temperature units conversion slope</td>
<td>1.000000e+00</td>
</tr>
<tr>
<td>19</td>
<td>T_bUnits</td>
<td>Temperature units conversion offset</td>
<td>0.000000e+00</td>
</tr>
</tbody>
</table>

* Factory calibration values are set at the factory.

Writing to Factory Calibration registers will void calibration!
MAINTENANCE/TROUBLESHOOTING

Maintenance/Sensor

There are no user-serviceable parts. If problems develop with sensor stability or accuracy, contact Seametrics. If the transducers have been exposed to hazardous materials, do not return them without notification and authorization.

Troubleshooting

<table>
<thead>
<tr>
<th>Problem</th>
<th>Probable Causes</th>
<th>Things to try…</th>
</tr>
</thead>
<tbody>
<tr>
<td>Erratic readings</td>
<td>Poor connection due to moisture between contacts in connector</td>
<td>Dry thoroughly. Be sure desiccant is fresh (see Maintenance section).</td>
</tr>
<tr>
<td></td>
<td>Loose or broken wires in connector</td>
<td>Repair or return for evaluation and repair</td>
</tr>
<tr>
<td></td>
<td>Damaged cable, cracked or fraying</td>
<td>Replace cable</td>
</tr>
<tr>
<td></td>
<td>Moisture in the unit</td>
<td>Return for evaluation and repair</td>
</tr>
<tr>
<td></td>
<td>Damaged transmitter</td>
<td>Return for evaluation and repair</td>
</tr>
<tr>
<td>Zero readings when pressurized</td>
<td>Poor connection due to moisture between contacts in connector</td>
<td>Dry thoroughly. Be sure desiccant is fresh (see Maintenance section).</td>
</tr>
<tr>
<td></td>
<td>Loose or broken wires in connector</td>
<td>Repair or return for evaluation and repair</td>
</tr>
<tr>
<td></td>
<td>Damaged cable, broken, cracked, or fraying</td>
<td>Replace cable</td>
</tr>
<tr>
<td></td>
<td>No apparent damage upon visual inspection</td>
<td>Return for evaluation and repair</td>
</tr>
</tbody>
</table>

Maintenance/Cable (for Compensation Wiring Option)

Cable can be damaged by abrasion, sharp objects, twisting, crimping, crushing, or pulling. Take care during installation and use to avoid cable damage.
LIMITED WARRANTY/DISCLAIMER - PT12-BV
BAROMETRIC/VACUUM SENSOR

A. Seller warrants that products manufactured by Seller when properly installed, used and maintained with a properly installed desiccant tube, shall be free from defects in material and workmanship. Seller’s obligation under this warranty shall be limited to replacing or repairing the part or parts or, at Seller’s option, the products which prove defective in material or workmanship within TWO (2) years from the date of delivery, provided that Buyer gives Seller prompt notice of any defect or failure and satisfactory proof thereof. Any defective part or parts must be returned to Seller’s factory or to an authorized service center for inspection. Buyer will prepay all freight charges to return any products to Seller’s factory, or any other repair facility designated by Seller. Seller will deliver replacements for defective products to Buyer (ground freight prepaid) to the destination provided in the original order. Products returned to Seller for which Seller provides replacement under this warranty shall become the property of Seller.

This limited warranty does not apply to lack of performance caused by abrasive materials, corrosion due to aggressive fluids, mishandling or misapplication. Seller’s obligations under this warranty shall not apply to any product which (a) is normally consumed in operation, or (b) has a normal life inherently shorter than the warranty period stated herein.

In the event that equipment is altered or repaired by the Buyer without prior written approval by the Seller, all warranties are void. Equipment and accessories not manufactured by the Seller are warranted only to the extent of and by the original manufacturer’s warranty.

THE FOREGOING WARRANTIES ARE IN LIEU OF ALL OTHER WARRANTIES, WHETHER ORAL, WRITTEN, EXPRESSED, IMPLIED OR STATUTORY. IMPLIED WARRANTIES OF FITNESS AND MERCHANTABILITY SHALL NOT APPLY. SELLER’S WARRANTY OBLIGATIONS AND BUYER’S REMEDIES THEREUNDER (EXCEPT AS TO TITLE) ARE SOLELY AND EXCLUSIVELY AS STATED HEREIN. IN NO CASE WILL SELLER BE LIABLE FOR CONSEQUENTIAL DAMAGES, LABOR PERFORMED IN CONNECTION WITH REMOVAL AND REPLACEMENT OF THE SENSOR SYSTEM, LOSS OF PRODUCTION OR ANY OTHER LOSS INCURRED BECAUSE OF INTERRUPTION OF SERVICE. A NEW WARRANTY PERIOD SHALL NOT BE ESTABLISHED FOR REPAIRED OR REPLACED MATERIAL, PRODUCTS OR SUPPLIES. SUCH ITEMS SHALL REMAIN UNDER WARRANTY ONLY FOR THE REMAINDER OF THE WARRANTY PERIOD ON THE ORIGINAL MATERIALS, PRODUCTS OR SUPPLIES.

B. With respect to products purchased by consumers in the United States for personal use, the implied warranties including but not limited to the warranties of merchantability and fitness for a particular purpose, are limited to twenty four (24) months from the date of delivery.

Some states do not allow limitations on the duration of an implied warranty, so the above limitation may not apply to you. Similarly, some states do not allow the exclusion or limitation of consequential damages, so the above limitation or exclusion may not apply to you. This limited warranty gives you specific legal rights; however, you may also have other rights which may vary from state to state.